



# SKY BIDI POWER



Snap  
closure



Electronic  
limit switch



Two-way  
protocol



Radio control

SKY BIDI POWER Ø45mm | SKY BIDI POWER Ø59MM

# SKY BIDI POWER

Equipped with a two-way radio receiver, the limit switch is electronic and can be configured from the transmitter itself. They also include the POWER function for snap closure, specially designed for cassette awnings.

## REFERENCES



**SKY BIDI POWER Ø45mm**

**Ø45 mm**

20/15 BD.245.020



**SKY BIDI POWER Ø59MM**

**Ø59 mm**

80/12 BD.259.080

Electronic limit switch configurable from the transmitter.

Head with 12mm central hole for mounting on monoblock drawer.

For 40,43,50,56,60, 70 and 78mm axle.

Two-way radio receiver.

POWER pressure-closing function for box-type awnings.

Automatic path correction

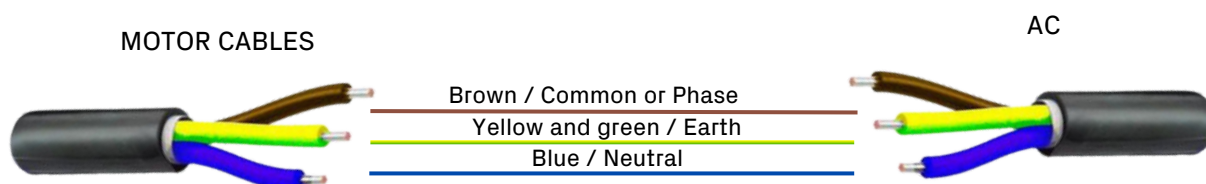
## TECHNICAL CHARACTERISTICS

Model	Par-nominal	Speed	Feeding	Nominal power	Amperage	Working time	Max rotations	Degree of protection	Length measurement	Max Weight
20/15	20 Nm	15 rpm	230v 50 hrz	161 W	0.69 A	4 min	∞	IP 44	602 mm	32 Kg
30/15	30 Nm	15 rpm	230v 50hrz	191 W	0.89 A	4 min	∞	IP 44	665 mm	50 Kg
50/12	50 Nm	12 rpm	230v 50hrz	228 W	0.99 A	4 min	∞	IP 44	712 mm	80 Kg

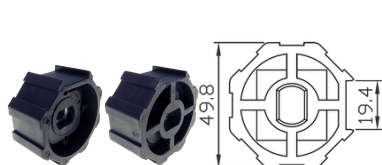
## MOTOR CONNECTORS



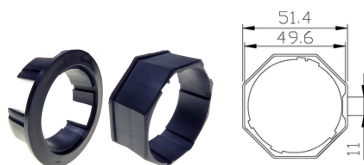
## ELECTRICAL DIAGRAM



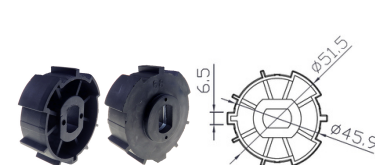
## ACCESSORIES FOR DIAMETER 45MM:



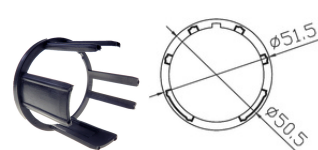
**50 octagonal pulley** | 61.005.010



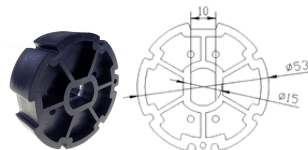
**Corona 50 octagonal** | 61.005.110



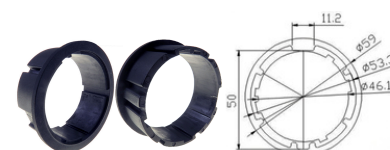
**DEPRAT 54 octagonal pulley** | 61.005.099



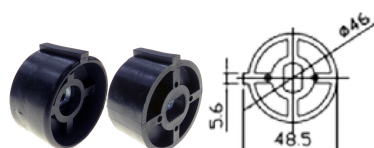
**Corona 54 octagonal DEPRAT** | 61.005.098



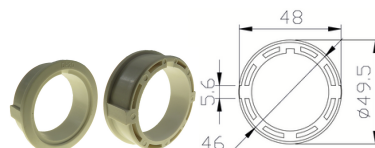
**Pulley 56** | 61.005.003



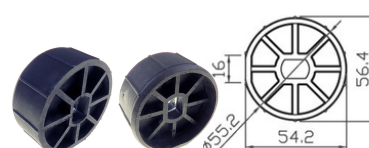
**Corona 56** | 61.005.103



**reinforced pulley 58** | 61.005.008



**Reinforced Crown 58** | 61.005.108



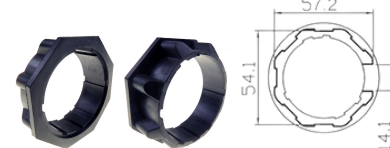
**Pulley 60 round** | 61.005.012



**reinforced octagonal pulley 60** | 40.005.011



**Corona 60 octagonal** | 61.005.111



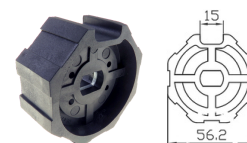
**Reinforced octagonal crown 60** | 40.005.111



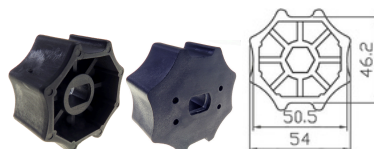
**Crown 60 curly** | 61.005.104



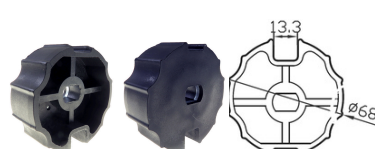
**Crown 60 round** | 61.005.112



**60 octagonal pulley** | 61.005.011



**Pulley 60 curled** | 61.005.004



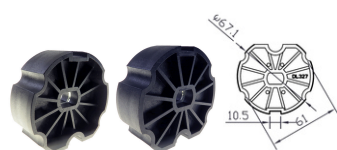
**Pulley 70 offset warhead** | 61.005.005



**Crown 70 off-centered ogive** | 61.005.105



## ACCESSORIES FOR DIAMETER 45MM:



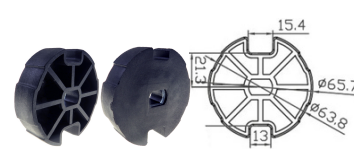
**Pulley 70 BAT warhead**

61.005.029



**Corona 70 BAT warhead**

61.005.129



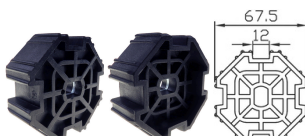
**Pulley 70 centered warhead**

61.005.014



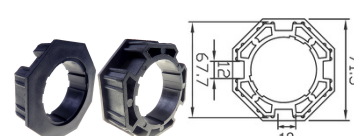
**Crown 70 centered ogive**

61.005.114



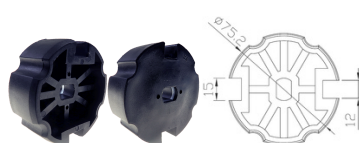
**70 octagonal pulley**

61.005.006



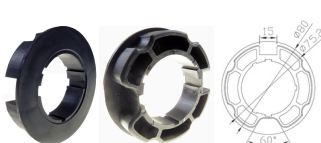
**Corona 70 octagonal**

61.005.106



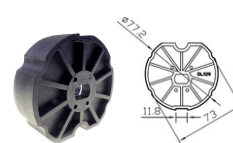
**Pulley 78 Warhead**

61.005.007



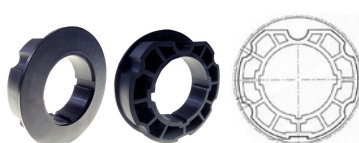
**Crown 78 Warhead**

61.005.107



**Pulley 80 BAT warhead**

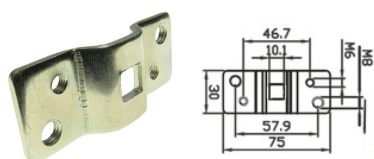
61.005.030



**Corona 80 BAT warhead**

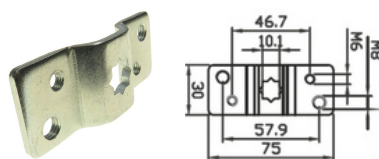
61.005.130

## MOUNTING BRACKETS:



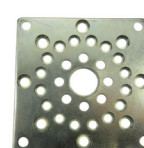
**CONSTRUCTION SUPPORT 45MM 2 AG.**

60.004.006



**45MM STAR CONSTRUCTION SUPPORT**

60.004.005



**DRAWER SUPPORT FOR 55/59MM**

60.004.059



**METAL SUPPORT 45 BD + BDP + WI**

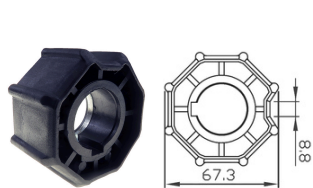
60.004.109



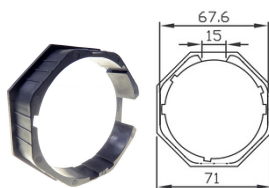
**SKY BIDI TYPE METAL SHEET DRAWER SUPPORT**

60.004.110

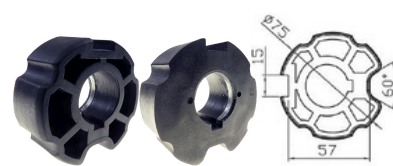
## ACCESSORIES FOR DIAMETER 59MM:



**70 Octagonal Pulley** | 61.005.016



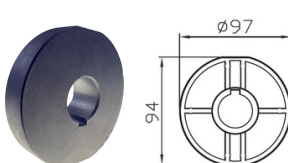
**Corona 70 Octagonal** | 61.005.116



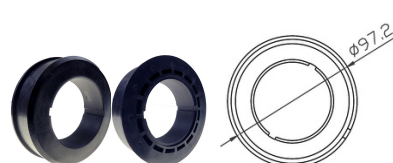
**Pulley 78 Off-center warhead** | 61.005.024



**Crown 78 Off-centered ogive** | 61.005.124



**100 round pulley** | 61.005.022



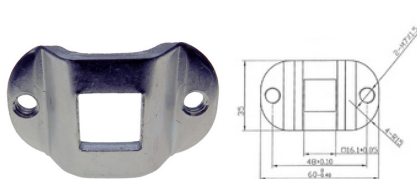
**Crown 100 round** | 61.005.122

## MOUNTING BRACKETS FOR 59MM:



**SQUARE DRAWER SUPPORT D.55/59**

60.004.066



**CONSTRUCTION SUPPORT 55 / 59 MM**

60.004.007



**CONSTRUCTION SUPPORT 55/59 MM  
STAR**

60.004.008

## COMPATIBLE WITH:



**KUMO WAVE**  
BD.100.001



**KIK1**  
BD.003.101



**KIK15**  
BD.003.115



**KIKWALLL**  
90.003.101



**KIKWALLL15**  
90.003.115



**NOX SOLAR  
WEATHER VANE**  
BD.002.124



**KIK SUN**  
BD.003.115SUN

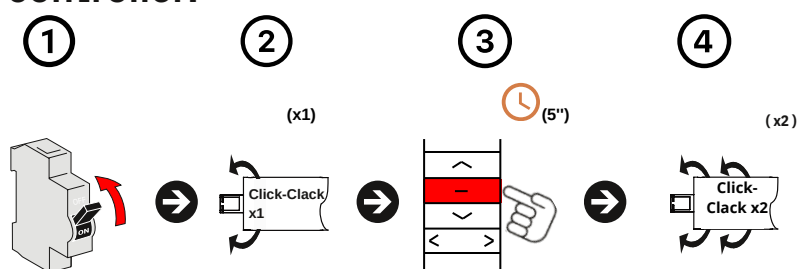


**KIK MOVE**  
BD.001.125

# INSTRUCTIONS:

## 1. LINK FIRST TRANSMITTER

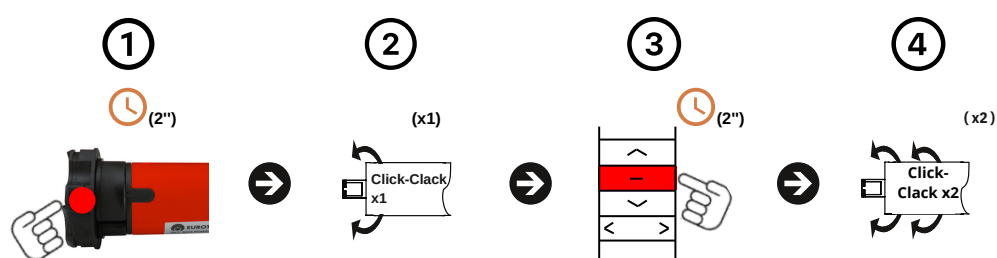
From the  
controller:



### Procedure:

1. To give current.
2. The motor will make a "CLICK-CLACK" sound (x1).
3. Press (STOP) on the remote control to record for five seconds (5'').
4. The motor will make a "CLICK-CLACK" sound (x1).

From the motor button:

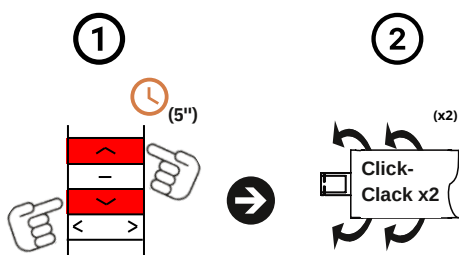


### Procedure:

1. Press the (PROG) button on the motor head for two seconds (2'').
2. The motor will make a "CLICK-CLACK" sound (x1) and a long beep (x1).
3. Press (STOP) on the transmitter to be recorded for two seconds (2'').
4. The motor will make two "CLICK-CLACK" sounds (x2) and three beeps (x3).

## 2. CHANGE OF ADDRESS

From the controller:

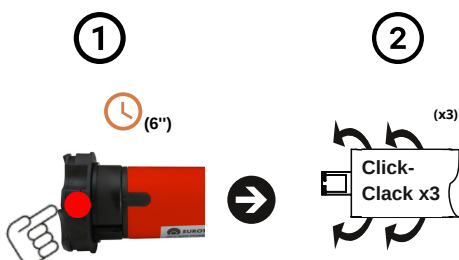


**Procedure:**

---

1. Press the (UP) + (DOWN) button on the remote control at the same time for five (5") seconds.
2. The motor will make two "CLICK-CLACK" sounds (x2).

From the motor button:



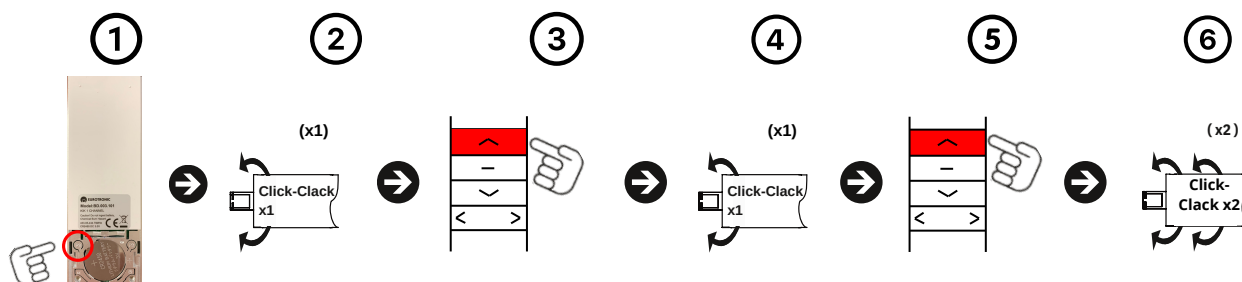
**Procedure:**

---

1. Press the (PROG) button on the motor head for six seconds (6").
2. The motor will make three "CLICK-CLACK" sounds (x3).

**Make sure the direction of rotation is correct before continuing with programming.**

### 3. SELECTION OF AWNING TYPE: PRESSURE CLOSURE OR STANDARD

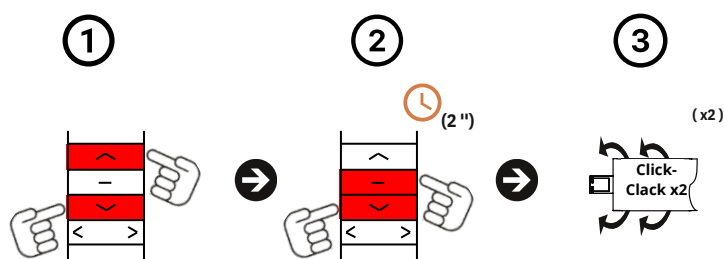


#### Procedure:

The Motor comes from the factory with the standard mode, following these instructions will alternate between the standard close and snap close modes.

1. We will press the button (P2) located behind the transmitter.
2. The motor will make a "CLICK-CLACK" sound (x1) and a beep sound (x1).
3. We will press the (UPLOAD) button.
4. The motor will make a "CLICK-CLACK" sound (x1) and a beep sound (x1).
5. We will press the (UPLOAD) button a second time to confirm.
6. The motor will make two "CLICK-CLACK" sounds (x2) and three beeps (x3).

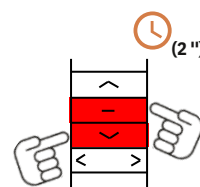
### 4. PROGRAM THE DOWNHILL LIMIT SWITCH



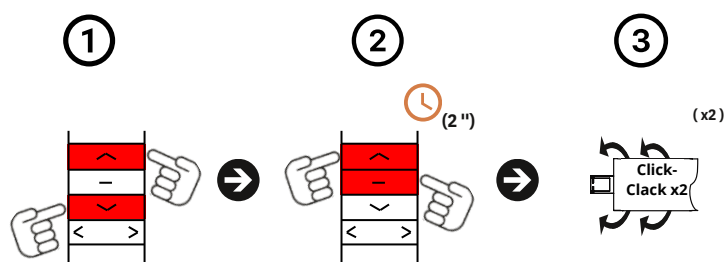
#### Procedure:

1. We will position the motor in the desired location using the (UP) or (DOWN) button on the transmitter. (if the up or down button is held down for 2 seconds, the movement will be automatic)
2. We will hold down the (DOWN + STOP) button for two seconds (2") to confirm.
3. The motor will make two "CLICK-CLACK" sounds (x2) and three beeps (x3).

**To modify the down stroke limit, press (DOWN + STOP) for 2 seconds and start the procedure again.**



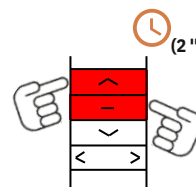
## 5. PROGRAM THE UPHILL LIMIT SWITCH



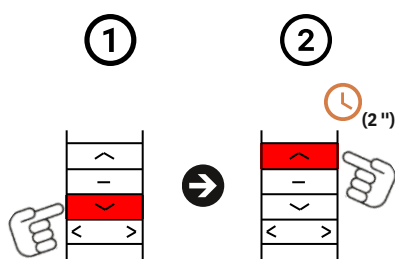
### Procedure:

1. We will position the motor in the desired location using the (UP) or (DOWN) button on the transmitter. (if the up or down button is held down for 2 seconds, the movement will be automatic)
2. We will hold down the (UP + STOP) button for two seconds (2") to confirm.
3. The motor will make two "CLICK-CLACK" sounds (x2) and three beeps (x3).

**To modify the down stroke limit, press (UP + STOP) for 2 seconds and start the procedure again.**



## 6. PROGRAM AUTOMATIC (BY PRESSURE) UPHILL LIMIT SWITCH

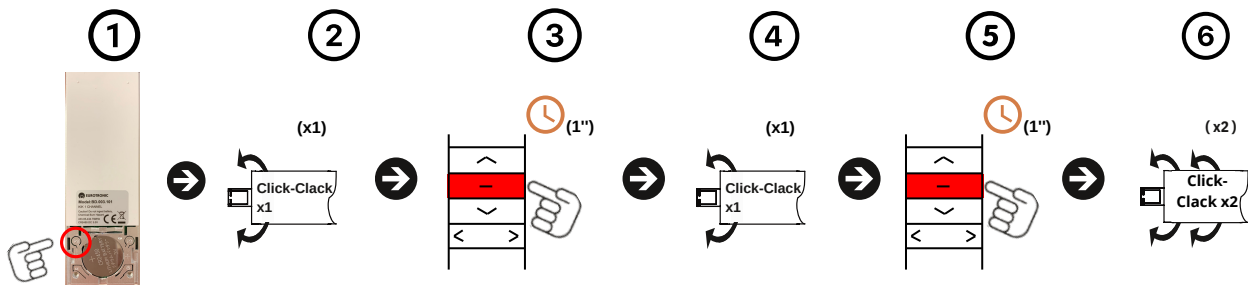


### Procedure:

**Make sure you have the lower limit switch set correctly.**

1. Open the motor a safe distance from the upper limit using the (DOWN) button.
2. We will hold down the (UP) button for two seconds (2") to confirm.

## 7. ADD/DELETE FAVORITE POSITION

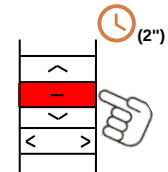


### Procedure:

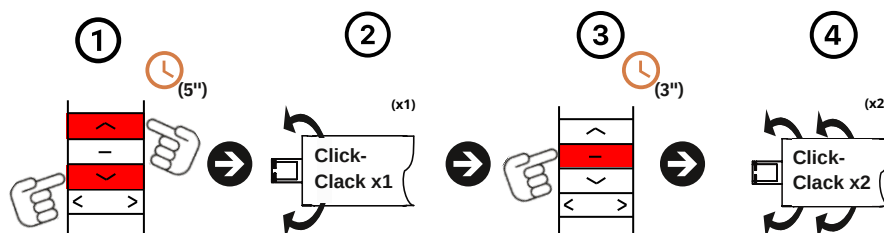
We will position the motor in the desired favorite position using the up or down button on the transmitter.

1. We will press the button (P2) located behind the transmitter.
2. The motor will make a "CLICK-CLACK" sound (x1) and a beep sound (x1).
3. We will press the central button (STOP).
4. The motor will make a "CLICK-CLACK" sound (x1) and a beep sound (x1).
5. We will press the central button (STOP) for the second time to confirm.
6. The motor will make two "CLICK-CLACK" sounds (x2) and three beeps (x3).

To search for the favorite position, press the (STOP) button for two seconds.



## 8. ACTIVATE/DEACTIVATE PULSE MOVEMENT



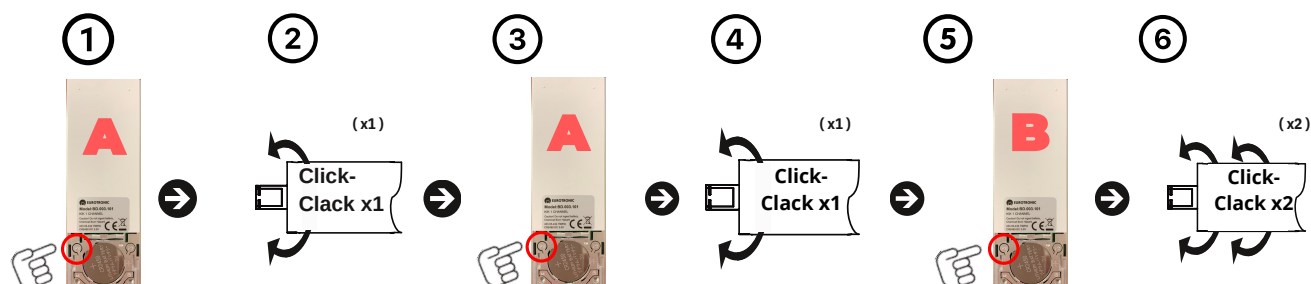
### Procedure:

1. Press the transmitter's (UP + DOWN) buttons at the same time for five seconds (5'').
  2. The motor will make a "CLICK-CLACK" sound (x1) and a beep sound (x1).
  3. Press the (STOP) button once (x1) to confirm.
- If the motor makes a "CLICK-CLACK" (x1) and a long beep (x1) it will be in pulse mode.
  - If the motor makes (x2) CLICK-CLACK and three beeps (x3) it will be in continuous mode.



## 9. LINK/REMOVE AN ADDITIONAL TRANSMITTER

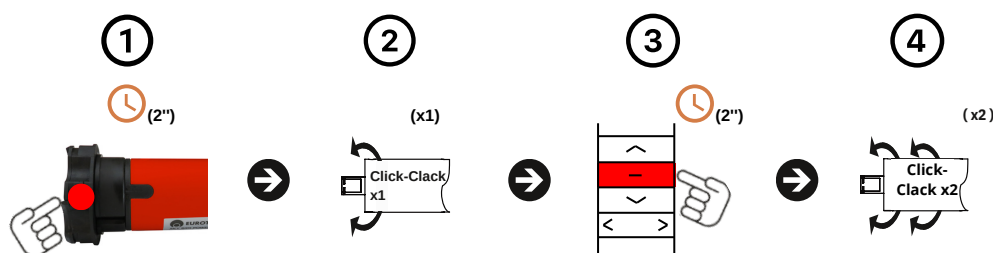
From the controller:



### Procedure:

1. Press the button (P2) located behind the already linked transmitter (A).
2. The motor will make a CLICK-CLACK (x1) and a beep (x1).
3. We will press the button (P2) of the same transmitter (A) again.
4. The motor will make a "CLICK-CLACK" sound (x1) and a beep sound (x1).
5. Then press the (P2) button on the new transmitter (B) to confirm.
6. The motor will make two "CLICK-CLACK" sounds (x2) and three beeps (x3).

From the motor button:

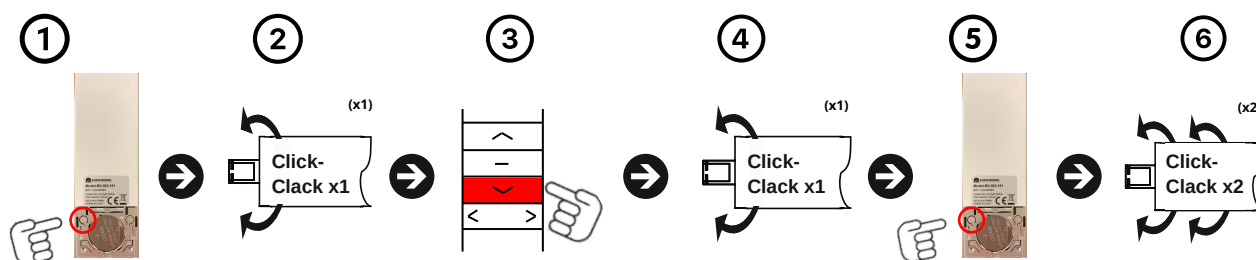


### Procedure:

1. Press the (PROG) button on the motor head for two seconds (2").
2. The motor will make a "CLICK-CLACK" sound (x1) and a long beep (x1).
3. Press (STOP) on the transmitter to be recorded for two seconds (2").
4. The motor will make two "CLICK-CLACK" sounds (x2) and three beeps (x3).

You can use either process to remove a bound emitter.

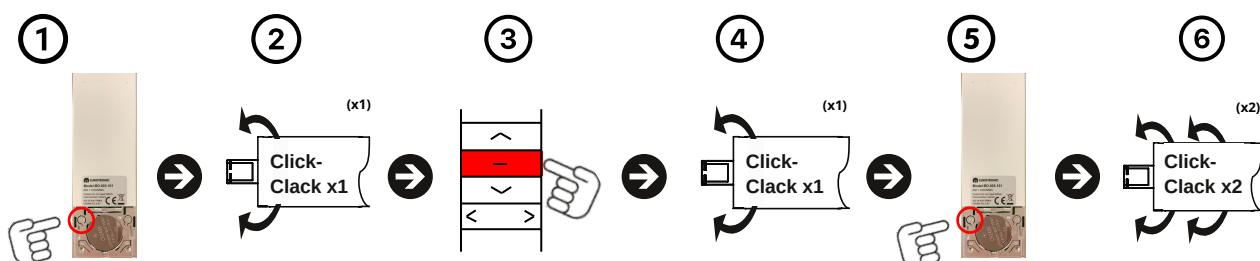
## 10. REMOVE ALL LIMIT SWITCHES



### Procedure:

1. Press the button (P2), of an already recorded transmitter, located on the back.
2. The motor will make a "CLICK-CLACK" sound (x1) and a beep sound (x1).
3. Next we will press the (DOWN) button.
4. The motor will make a "CLICK-CLACK" sound (x1) and a beep sound (x1).
5. We will press the (P2) button again to confirm.
6. The motor will make two "CLICK-CLACK" sounds (x2) and three beeps (x3).

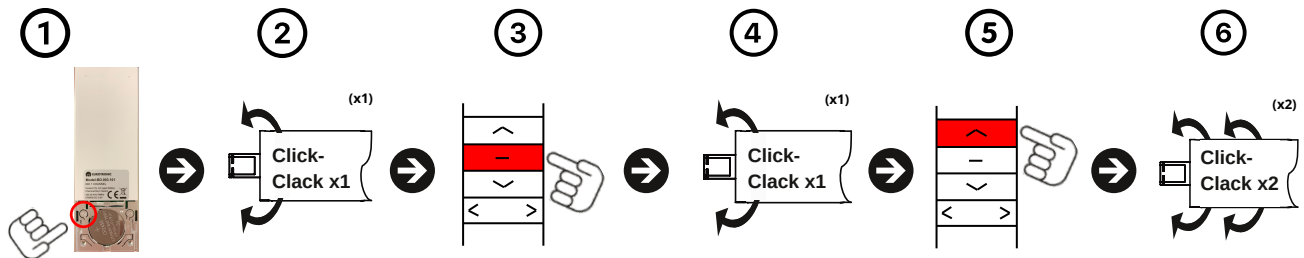
## 11. DELETE ALL TRANSMITTERS



### Procedure:

1. Press the button (P2), of an already recorded transmitter, located on the back.
2. The motor will make a "CLICK-CLACK" sound (x1) and a beep sound (x1).
3. Next we will press the central button (STOP).
4. The motor will make a "CLICK-CLACK" sound (x1) and a beep sound (x1).
5. We will press the (P2) button again to confirm.
6. The motor will make two "CLICK-CLACK" sounds (x2) and three beeps (x3).

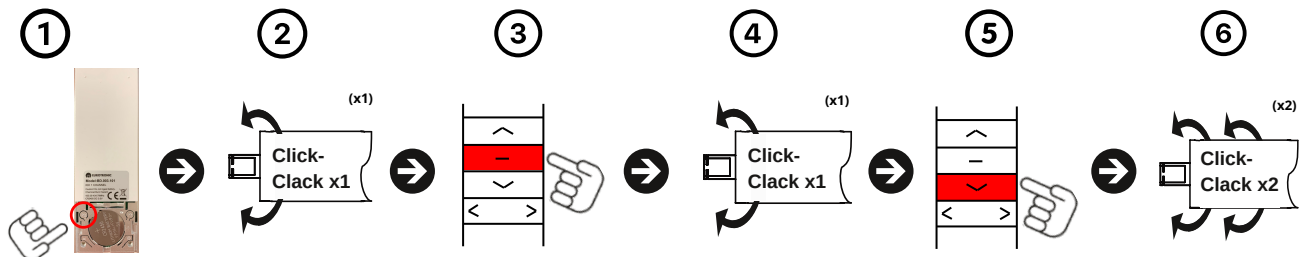
## 12. ENABLE/DISABLE RECOIL ON CLOSE



### Procedure:

1. Press the (P2) button on the transmitter.
2. The motor will make a "CLICK-CLACK" sound (x1) and a beep sound (x1).
3. Next we will press the (STOP) button.
4. The motor will make a "CLICK-CLACK" sound (x1) and a beep sound (x1).
5. Press the (UP) button to confirm.
6. The motor will make a "CLICK-CLACK" sound (x1) and a long beep (x1).

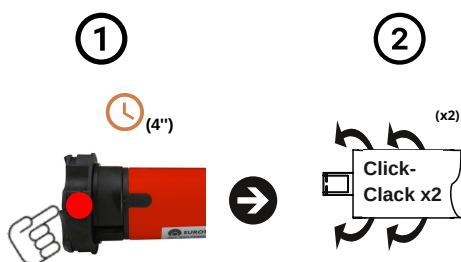
## 13. ENABLE/DISABLE KICKBACK AT OPENING



### Procedure:

1. Press the (P2) button on the transmitter.
2. The motor will make a "CLICK-CLACK" sound (x1) and a beep sound (x1).
3. Next we will press the (STOP) button.
4. The motor will make a "CLICK-CLACK" sound (x1) and a beep sound (x1).
5. Press the (DOWN) button to confirm.
6. The motor will make a "CLICK-CLACK" sound (x1) and a long beep (x1).

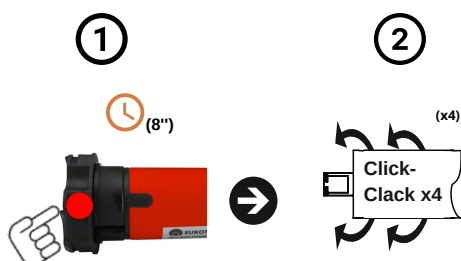
## 14. RADIO BLOCKING



### Procedure:

1. Press the (PROG.) button on the motor head for ten seconds (4").
2. The motor will make two "CLICK-CLACK" sounds (x2).

## 15. RESET TO FACTORY MODE



### Procedure:

1. Press the (PROG.) button on the motor head for eight seconds (8").
2. The motor will make four "CLICK-CLACK" sounds (x4).

**This motor travels between the upper and lower limit switches every 50 cycles. The motor automatically calibrates itself to ensure proper motor operation.**

**The automatic calibration cycle consists of a series of short ups and downs to confirm the limit switch positions.**



[www.eurotronic-europe.com](http://www.eurotronic-europe.com)

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